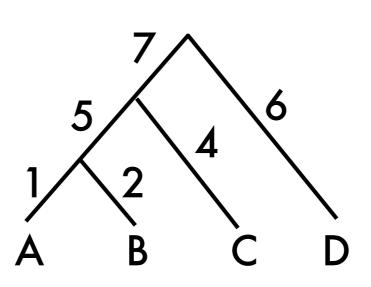
Averaging Metric Trees

Ezra Miller Megan Owen Scott Provan

Duke NCSU/SAMSI UNC

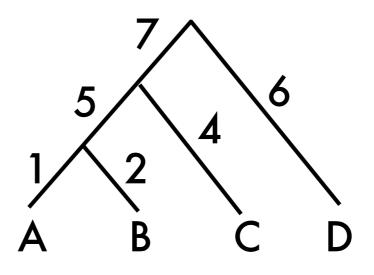
Phylogenetic Trees

• a metric tree:

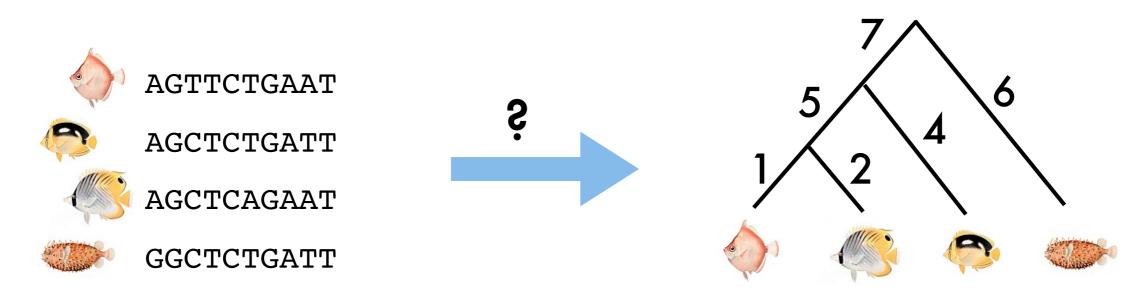


Phylogenetic Trees

• a metric tree:

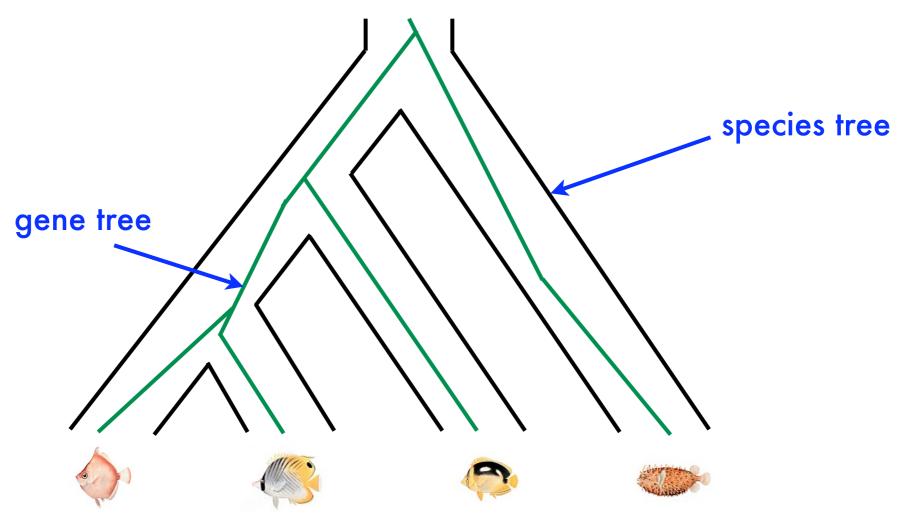


• a phylogenetic tree:



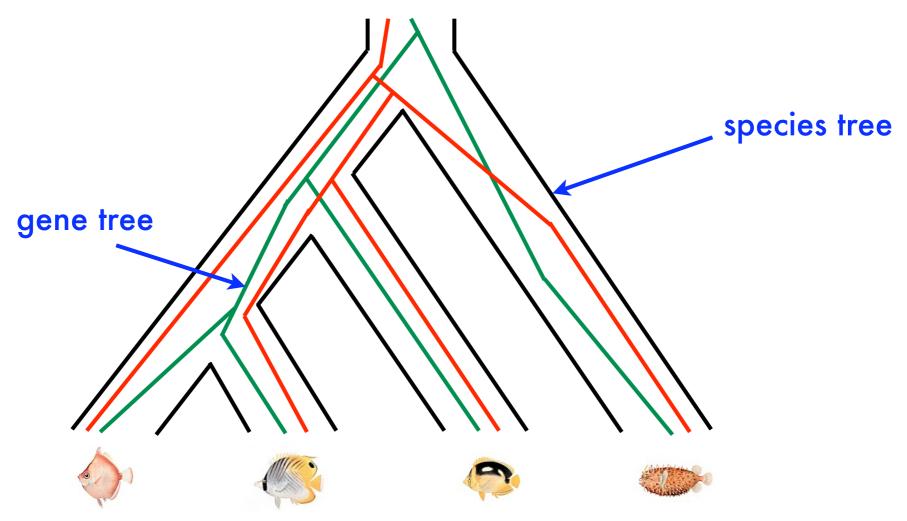
Gene and Species Trees

 want species trees, but DNA gives us gene trees



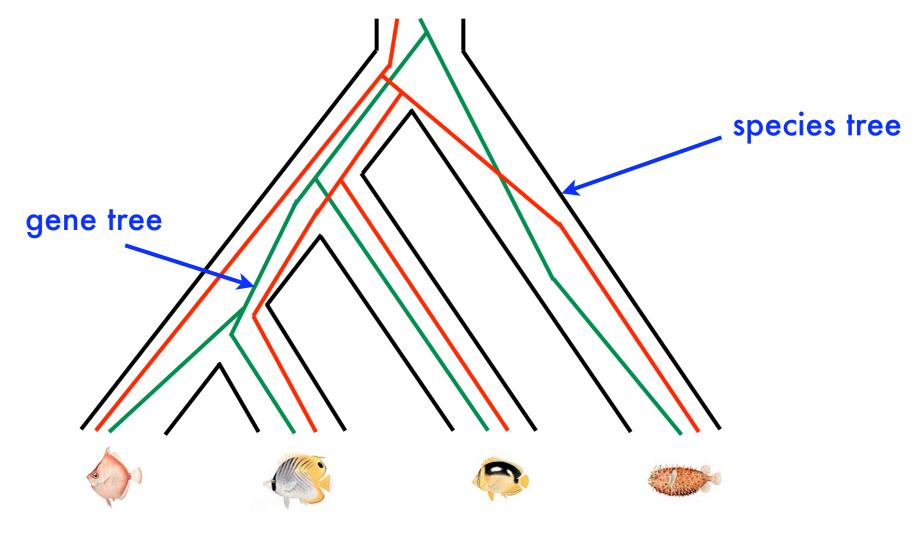
Gene and Species Trees

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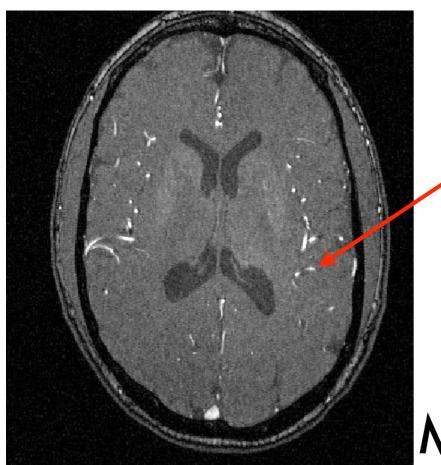
Gene and Species Trees

 want species trees, but DNA gives us gene trees



• average of gene trees = species tree ?

Comparing brains



With Steve Marron, Ipek Oguz, Scott Provan, Martin Styner (all UNC)

blood vessel

MRI scans →

tree representing arteries in a brain

- how do we compare trees to determine changes in brain due to aging or disease?
 - moving average

Figures from Steve Marron



- goal:
 - compute a meaningful average of a set of metric trees

- metric tree parameters:
 - tree topology
 - edge lengths
- so not a standard statistical problem!

Tree Space Framework

continuous, polyhedral space of phylogenetic trees

 Geometry of the space of phylogenetic trees, Billera, Holmes, and Vogtmann, 2001.

= tree complex

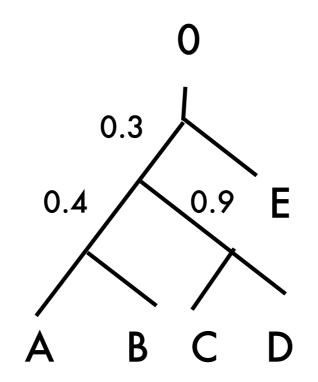
- Shellability of complexes of trees, Trappmann and Ziegler, 1998.
- The tree representation of σ_{n+1} , Robinson and Whitehouse, 1996.

+ metric (geodesic distance)

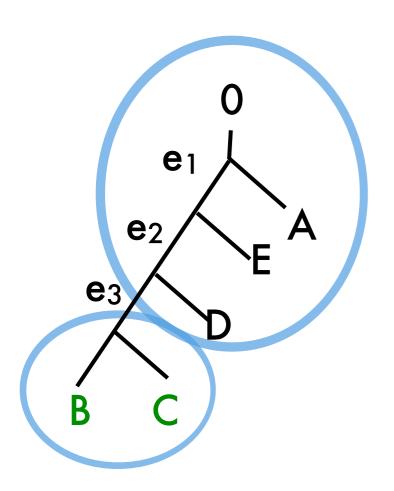
computable in polynomial time (Owen and Provan, 2009)

Tree Space \mathbb{T}_n

- trees in \mathbb{T}_n have:
 - n leaves
 - interior edges with lengths ≥0







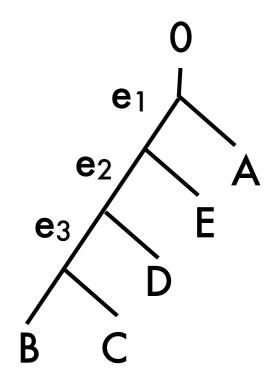
each interior edge induces a split
a split is a partition of the set of leaves plus the root 0:

$$e_3 = \{ \{B,C\}, \{0,A,E,D\} \}$$

or $e_3 = BC \mid OAED$

Split Compatibility

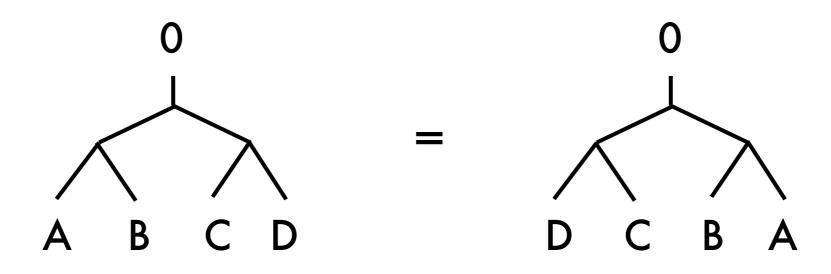
 e_x = X | X' is compatible with e_y = Y | Y' if there exists a tree containing both splits



ex. $e_3 = BC \mid OAED$ is compatible with $e_2 = BCD \mid OAE$ but not with $f = AB \mid OCDE$

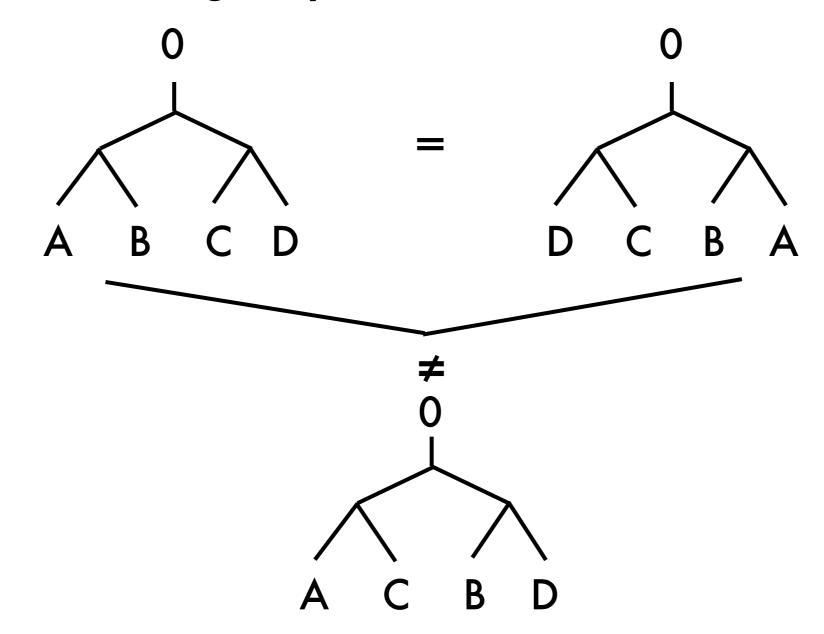
The trees

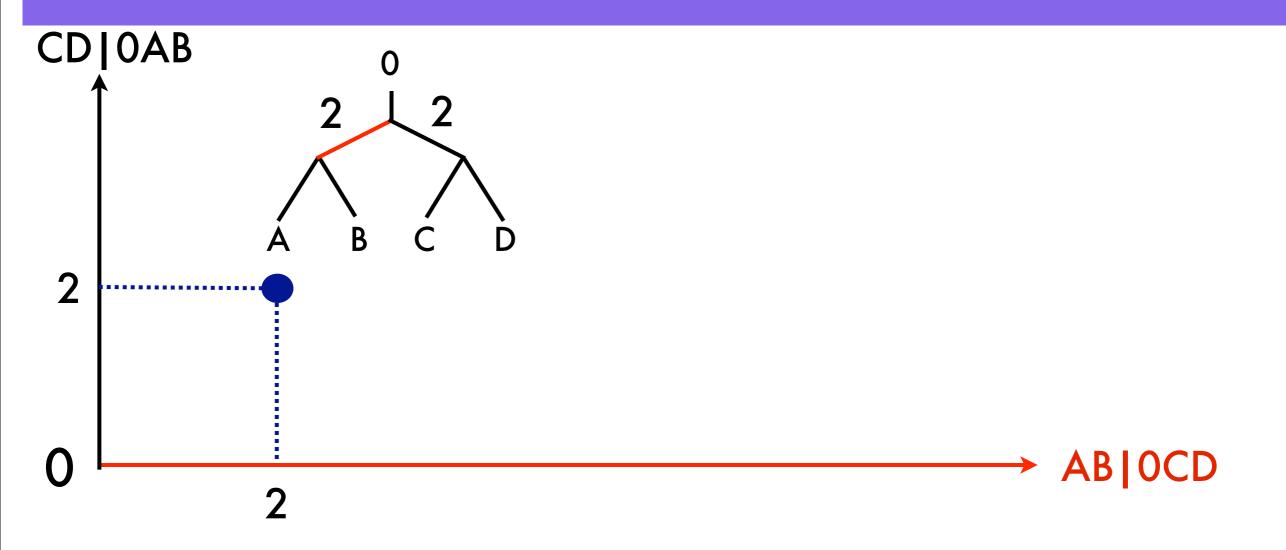
embedding in plane irrelevant

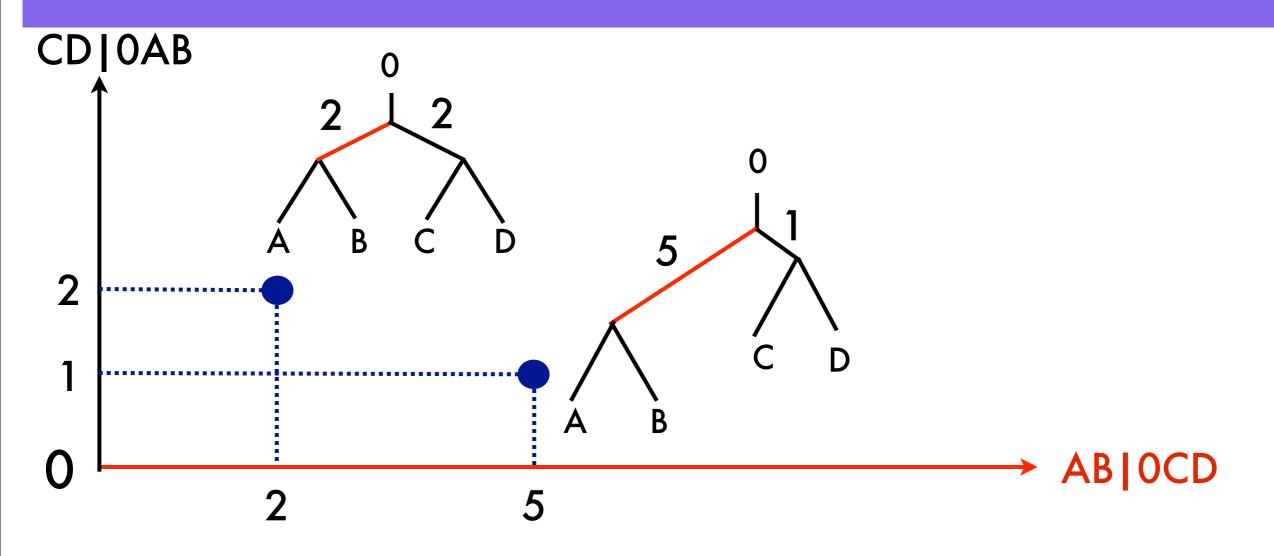


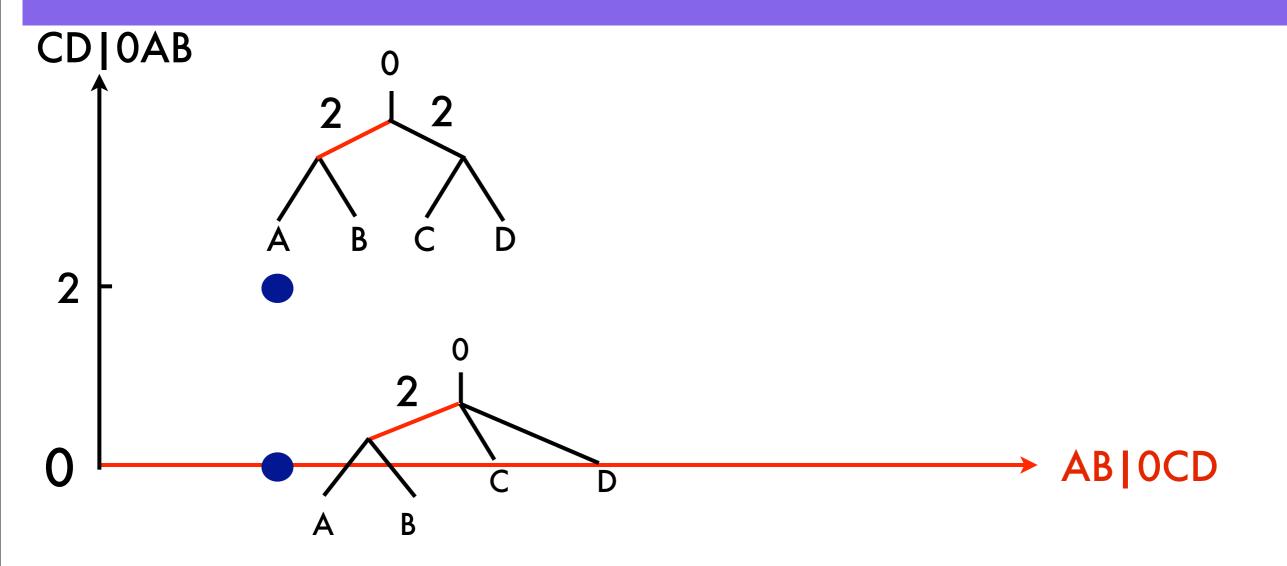
The trees

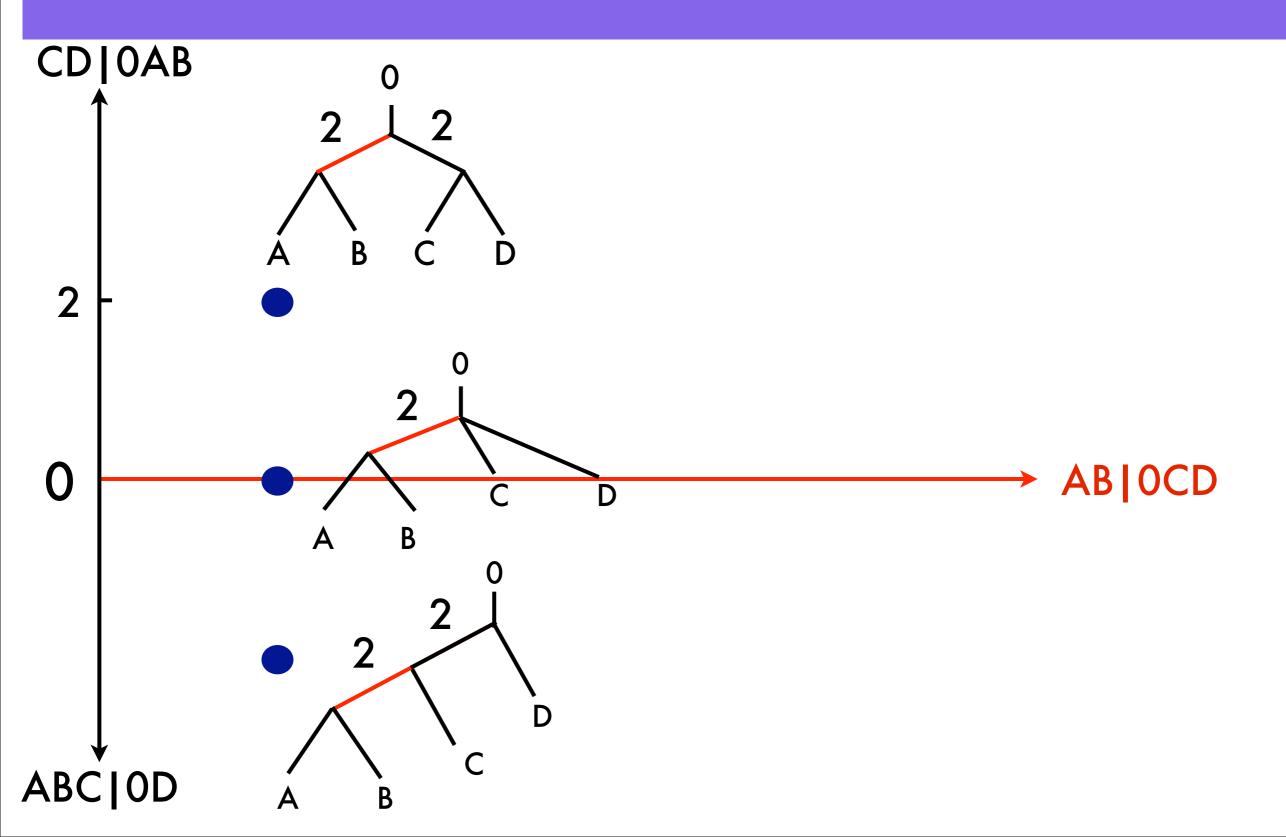
embedding in plane irrelevant

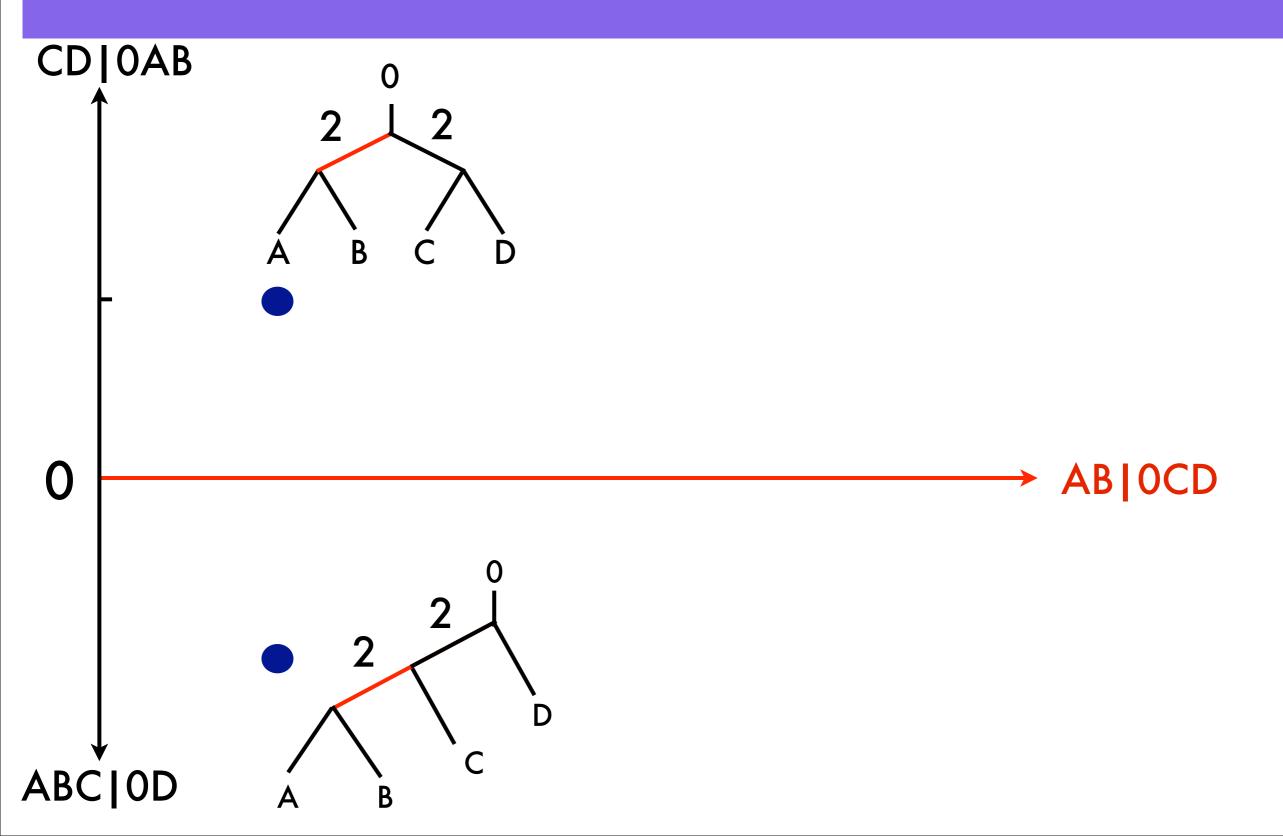


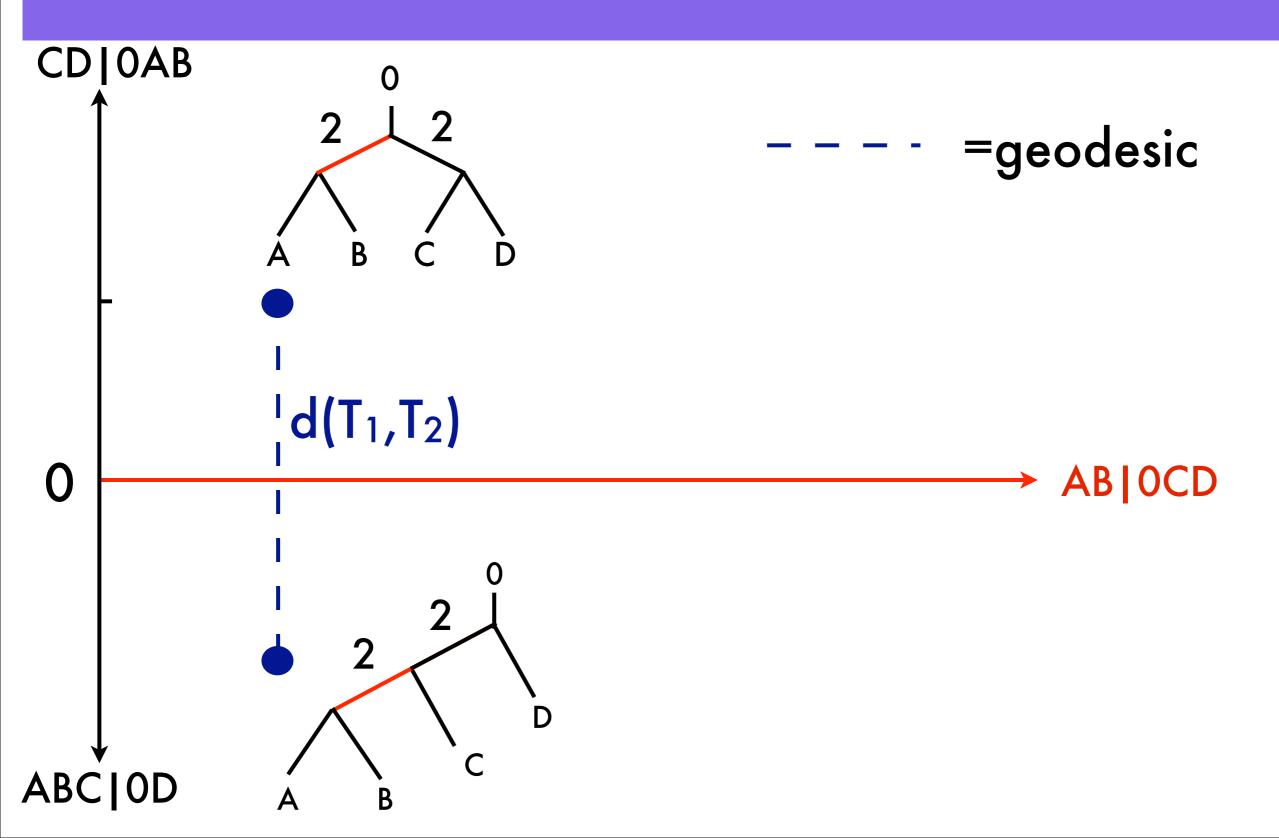


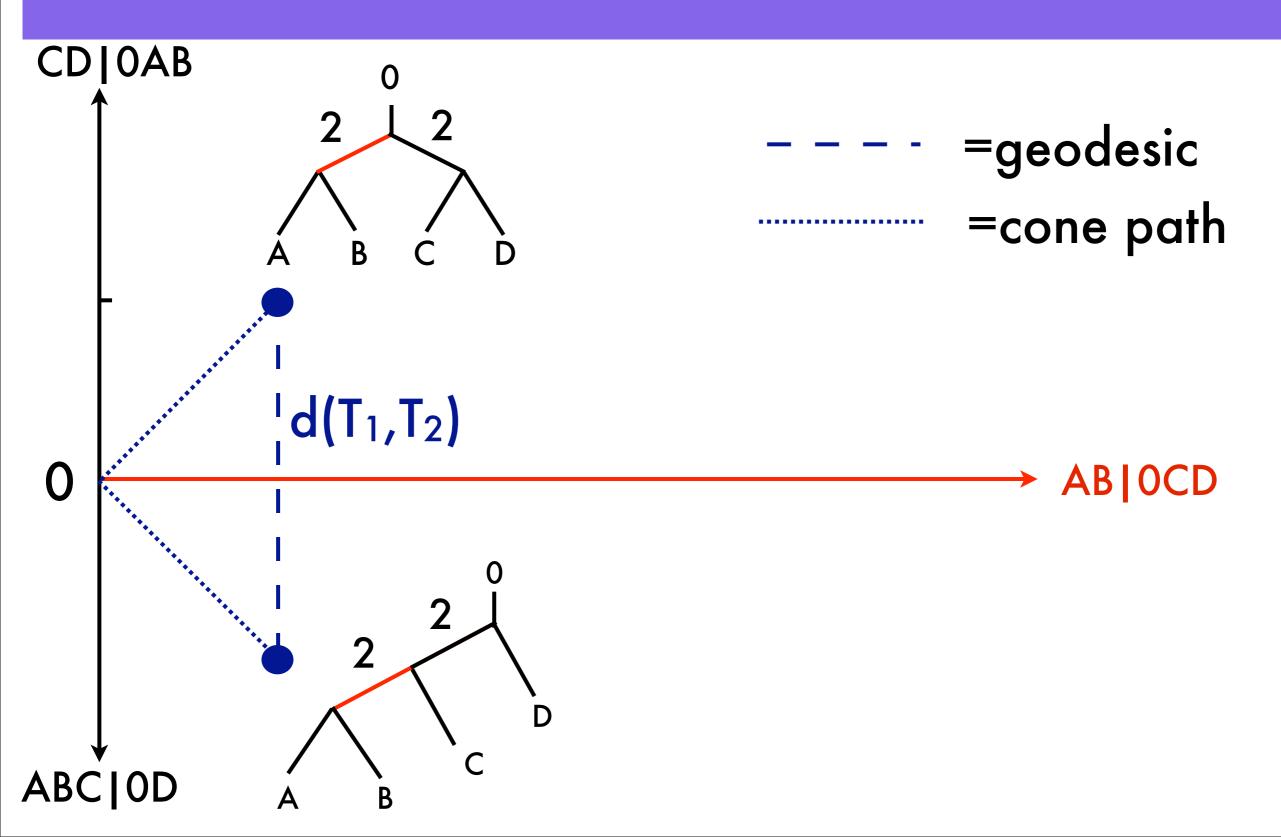


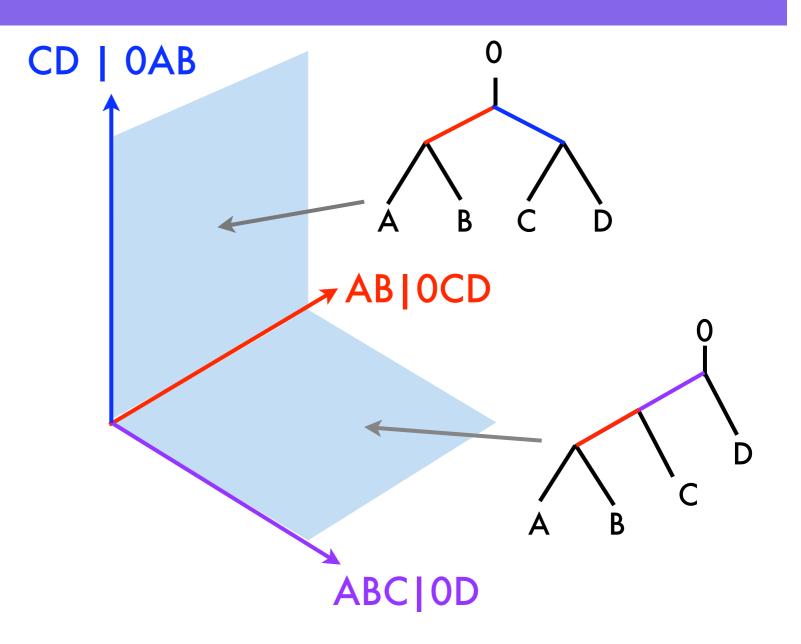


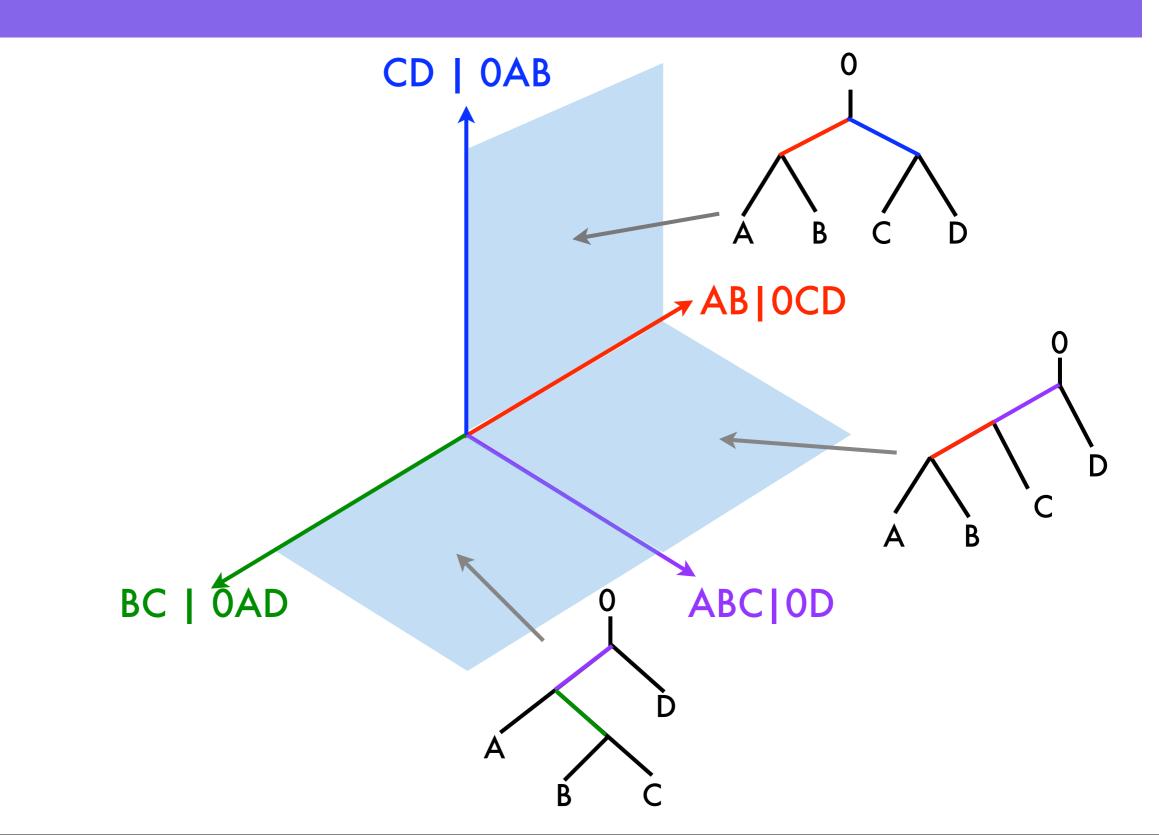




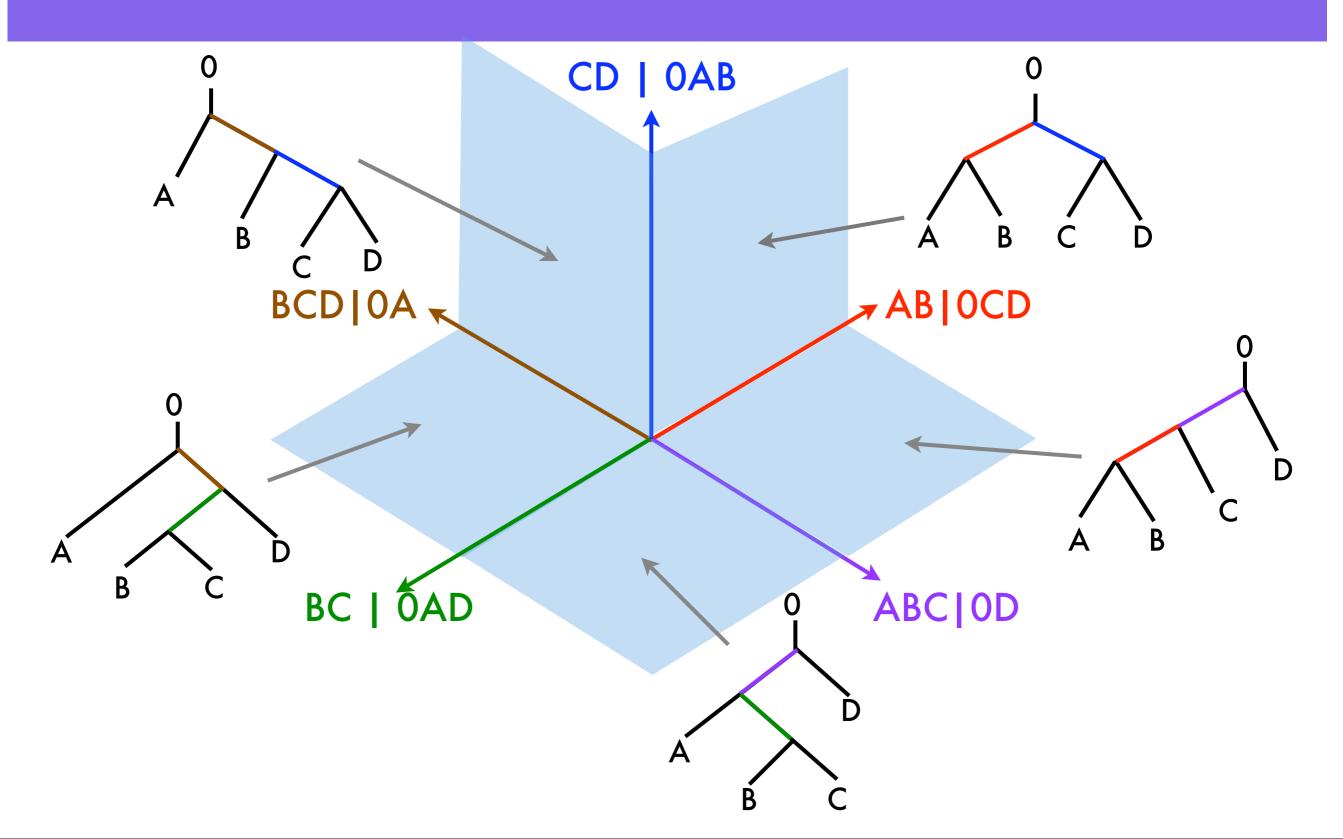


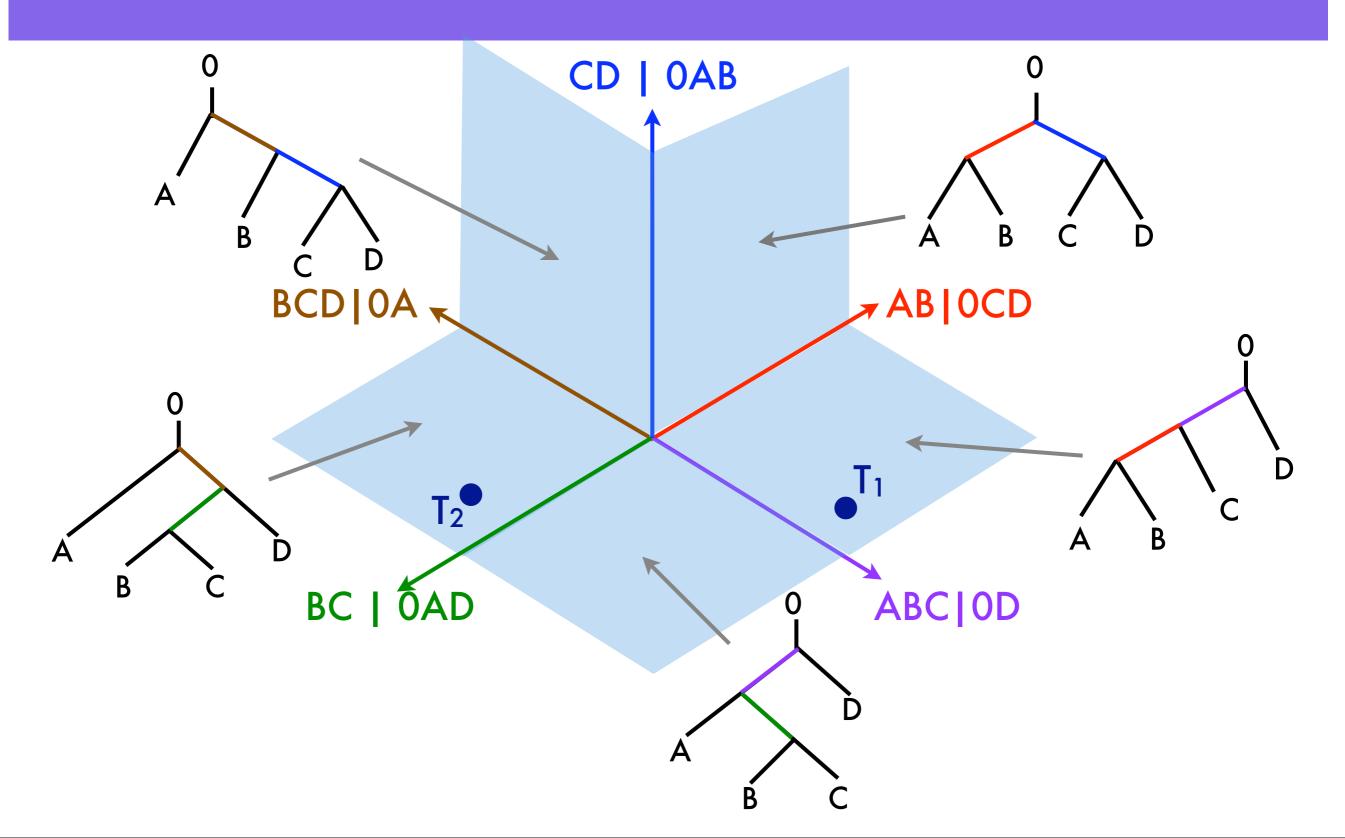


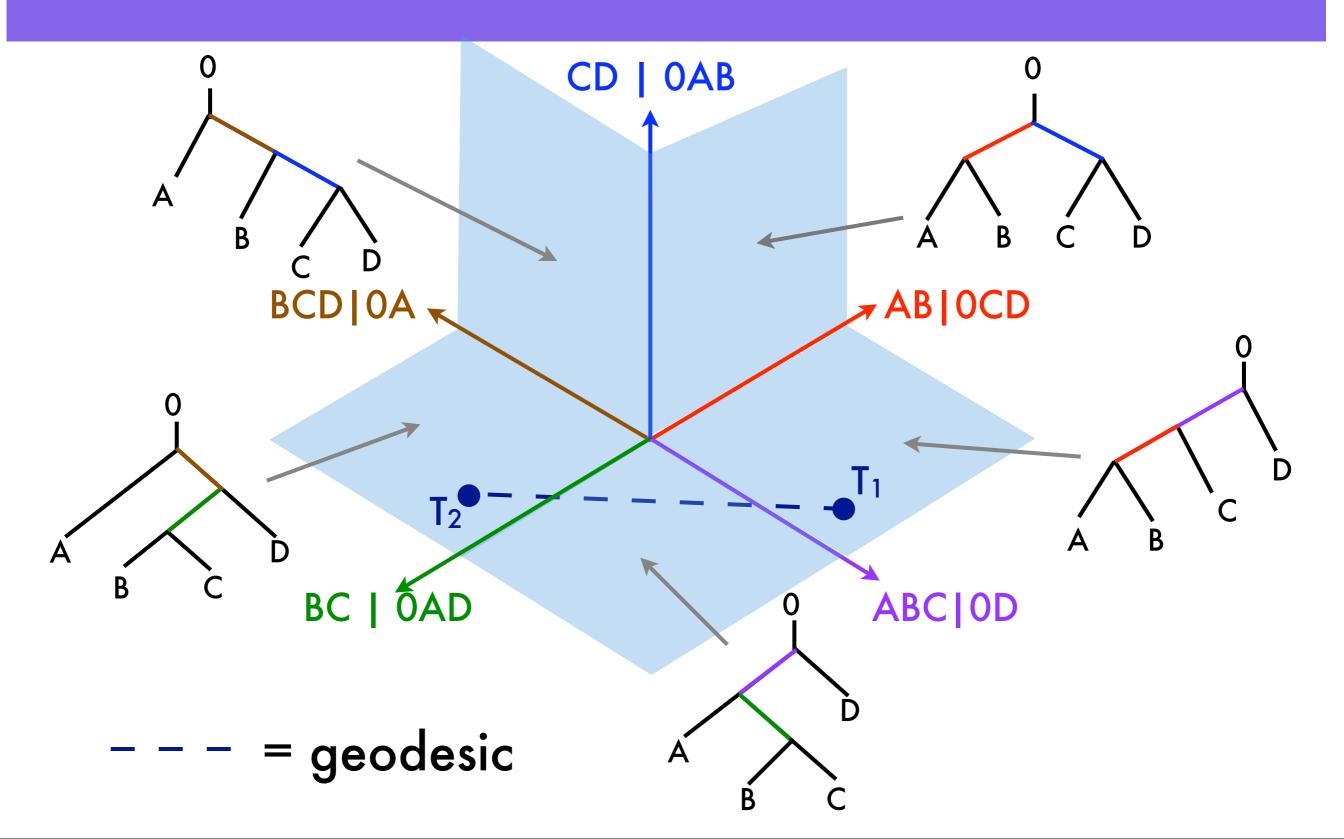


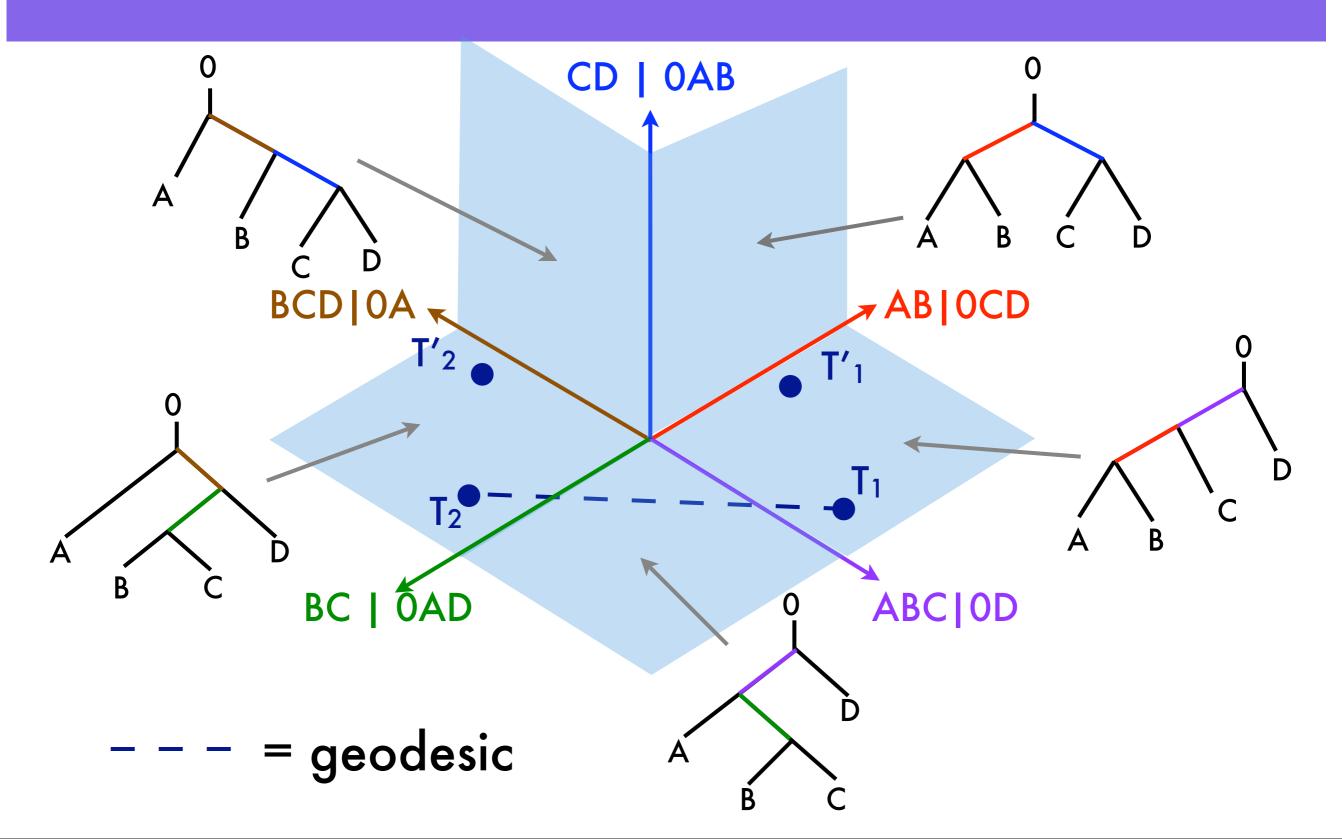


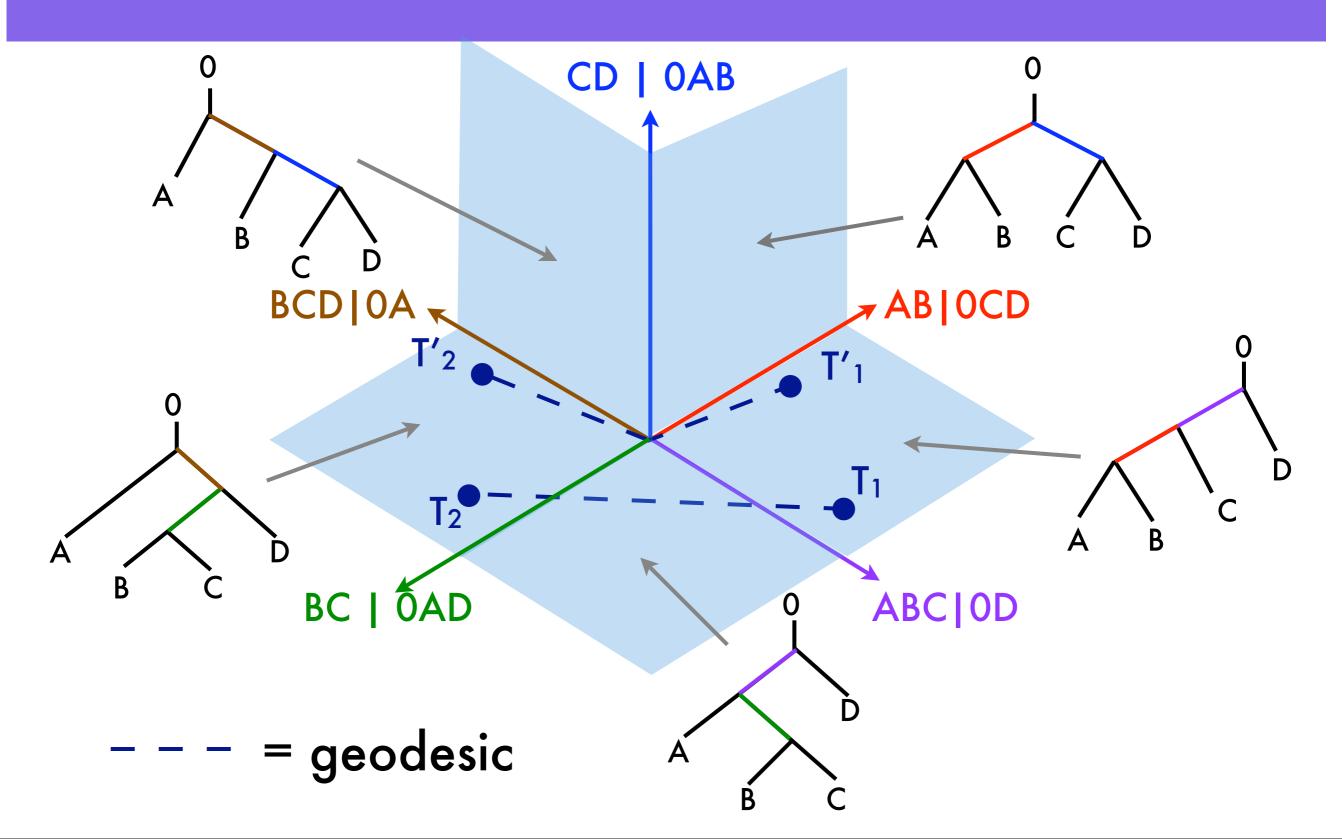
Structure of \mathbb{T}_4 0 CD | OAB Ď В AB|OCD BCD | 0A D Ċ B Α Ď Α Ċ В BC | ÔAD ABC|0D 0 Ď Α











\mathbb{T}_n is CAT(0)

- CAT(0) space (non-positively curved)
 - ⇒ unique geodesic (shortest path

between two points)

- ⇒ well-defined mid-point tree
- geodesic distance = length of geodesic
 between two trees T₁ and T₂, in
 - computable in polynomial time O(n⁴)
 (Owen and Provan, 2010)

Average or Mean Trees

- mean tree
 - = center of mass of given set of trees
 - = tree T' minimizing sum of square geodesic distances from T' to each tree in a given set ${\cal T}$

$$\underset{\mathsf{T}'}{\operatorname{\mathsf{mean tree}}} = \underset{\mathsf{T}'}{\operatorname{argmin}} \underset{T \in \mathcal{T}}{\sum} d(T,T')^2$$

- $m_0 = T_1$
- ith iteration:
 - randomly choose tree T_i from given set

•
$$m_i = \frac{1}{i+1}$$
 (geodesic from m_{i-1} to T_i)

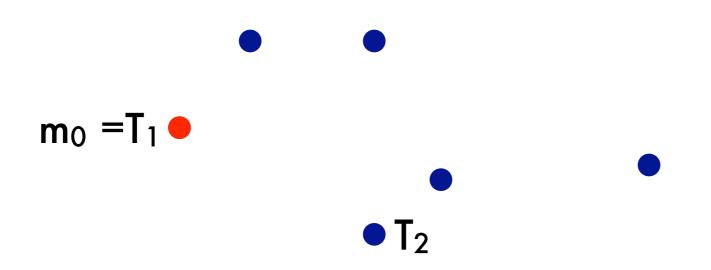
Theorem (Sturm, 2003): the following algorithm converges to the mean tree:

• $m_0 = T_1$

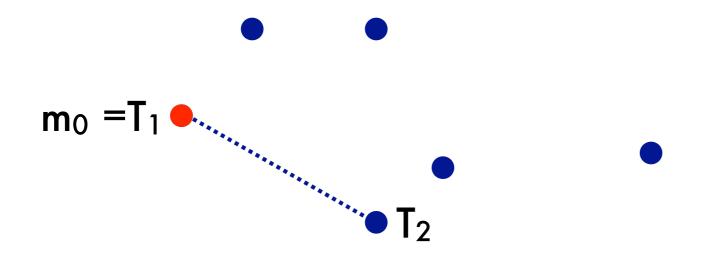
 $m_0 = T_1 \bullet$

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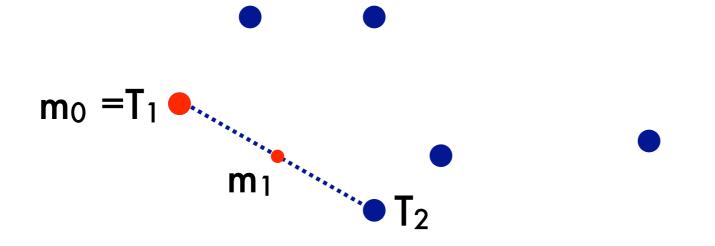


- $m_0 = T_1$
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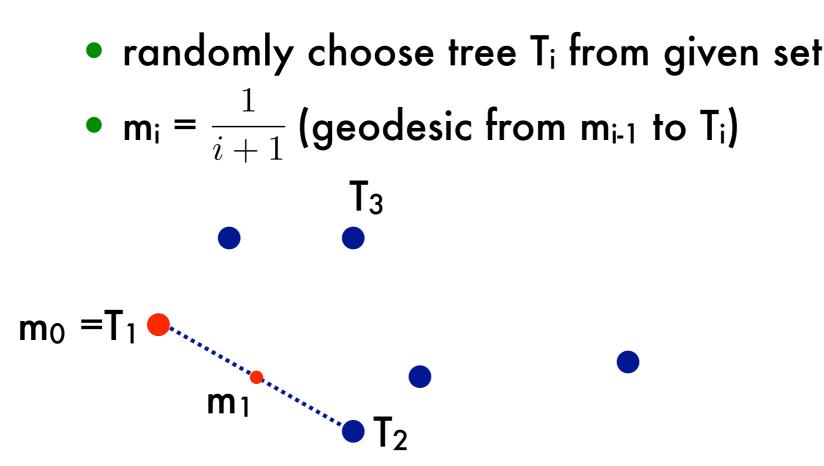


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- ith iteration:
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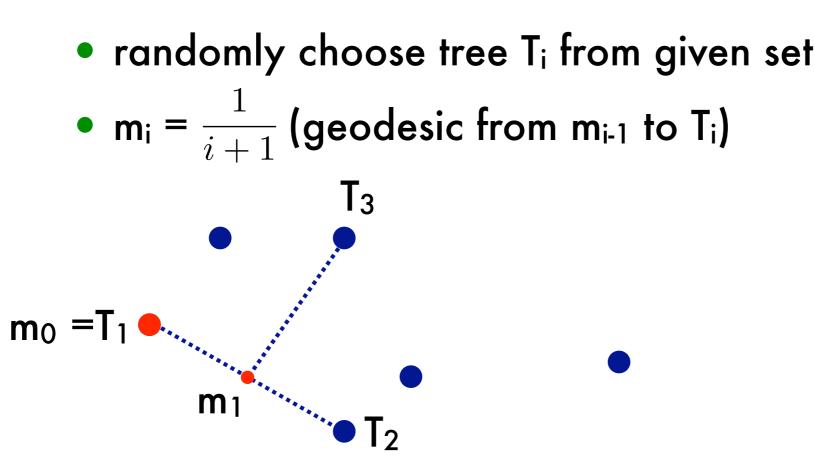
•
$$m_i = \frac{1}{i+1}$$
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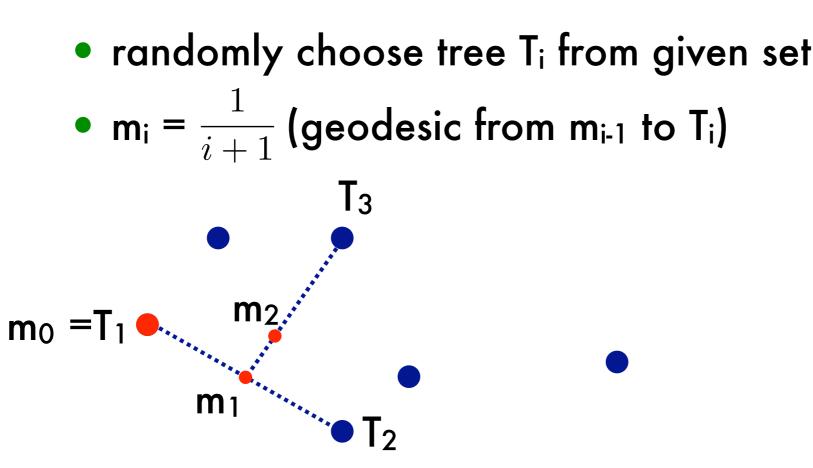
- $m_0 = T_1$
- ith iteration:



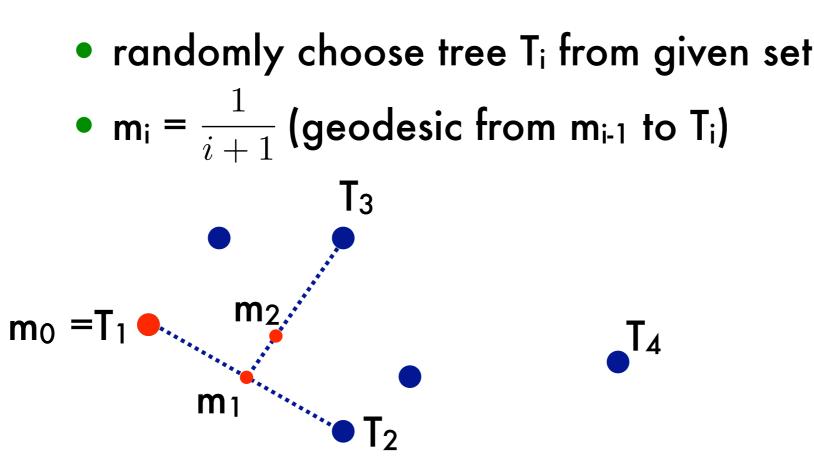
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- ith iteration:



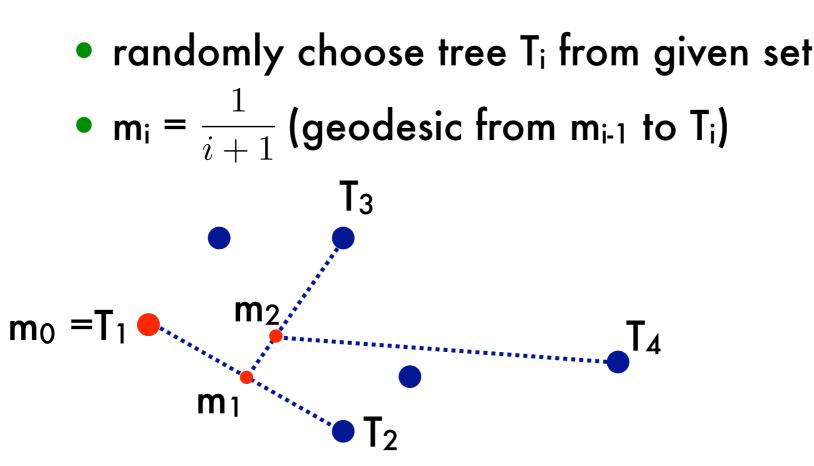
- $m_0 = T_1$
- ith iteration:



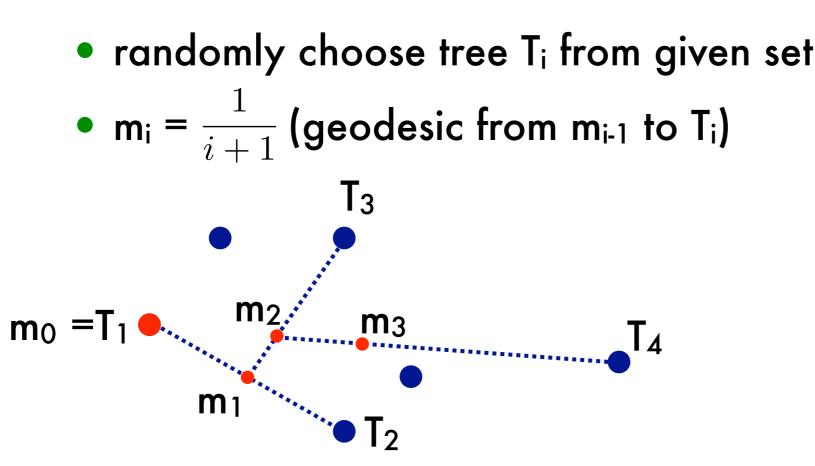
- $m_0 = T_1$
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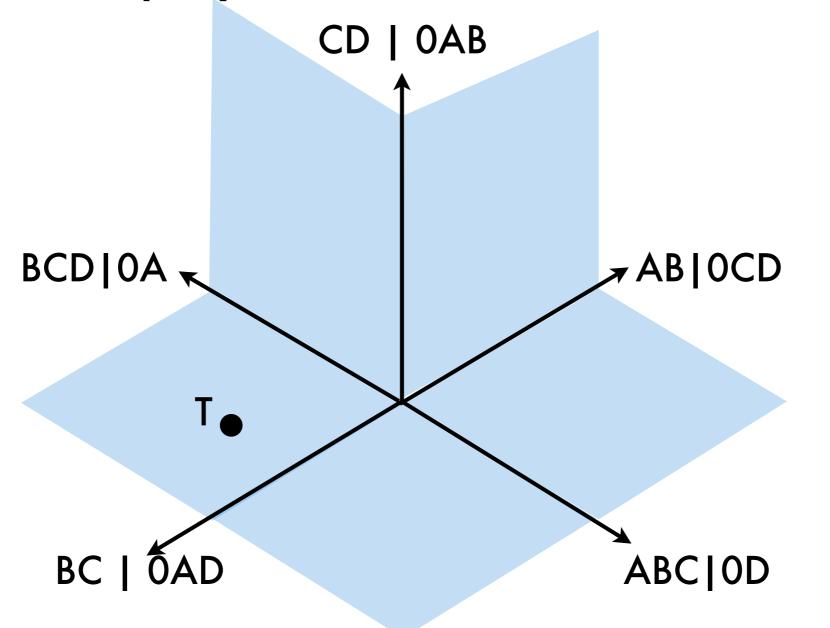


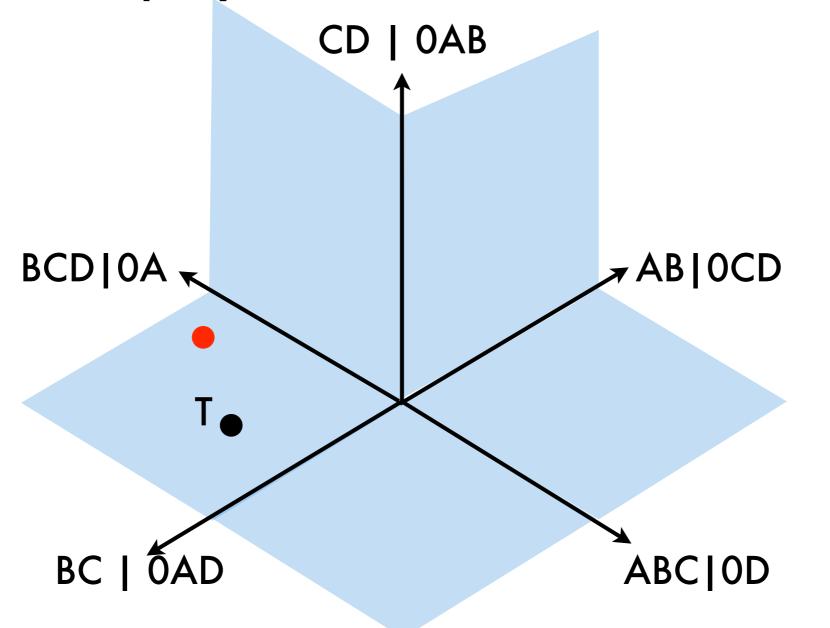
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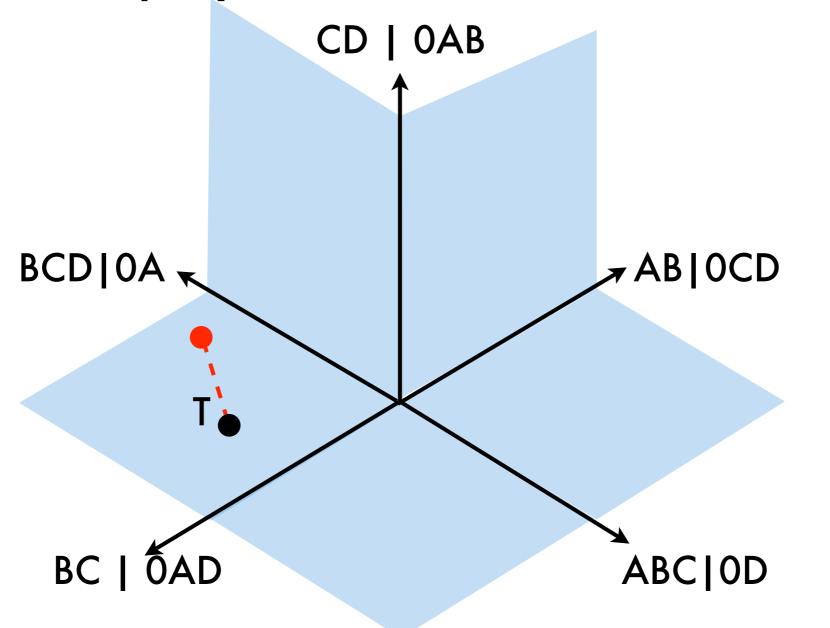


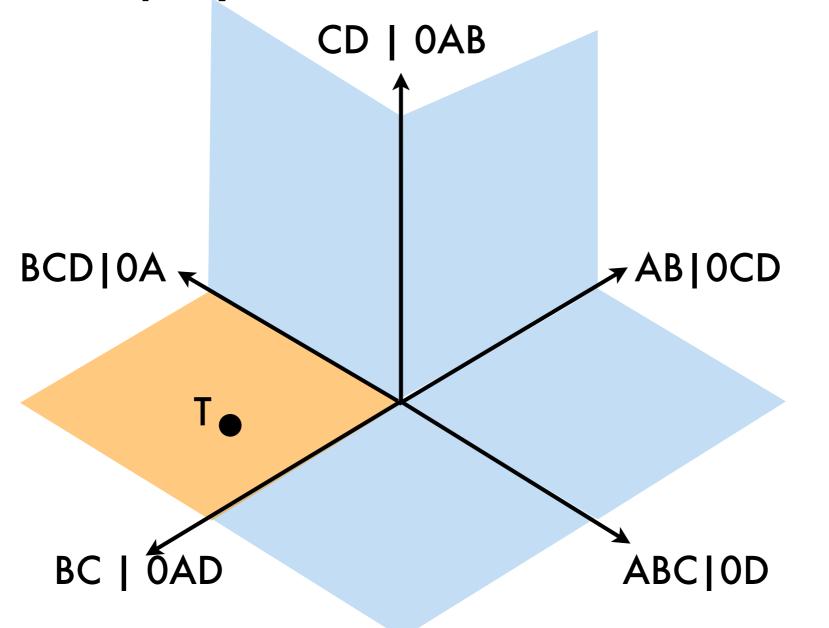
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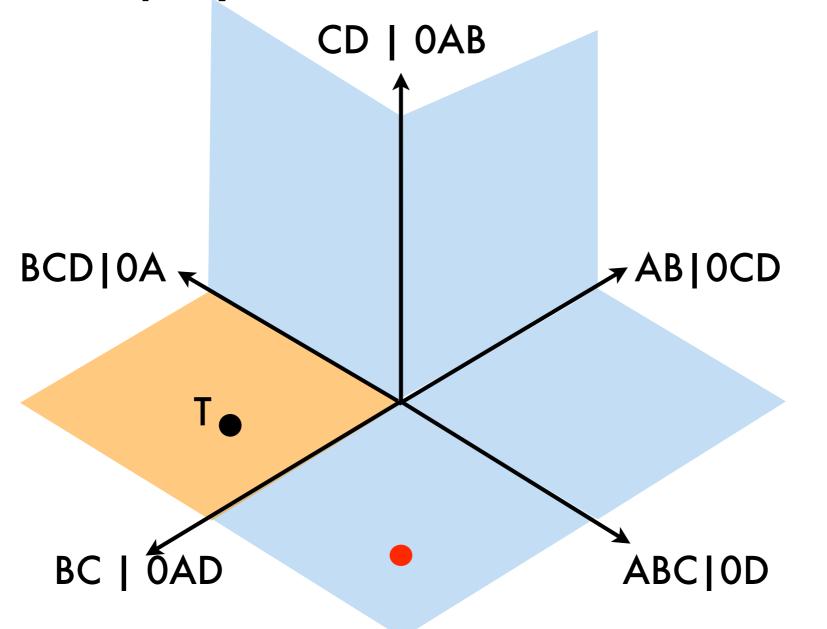


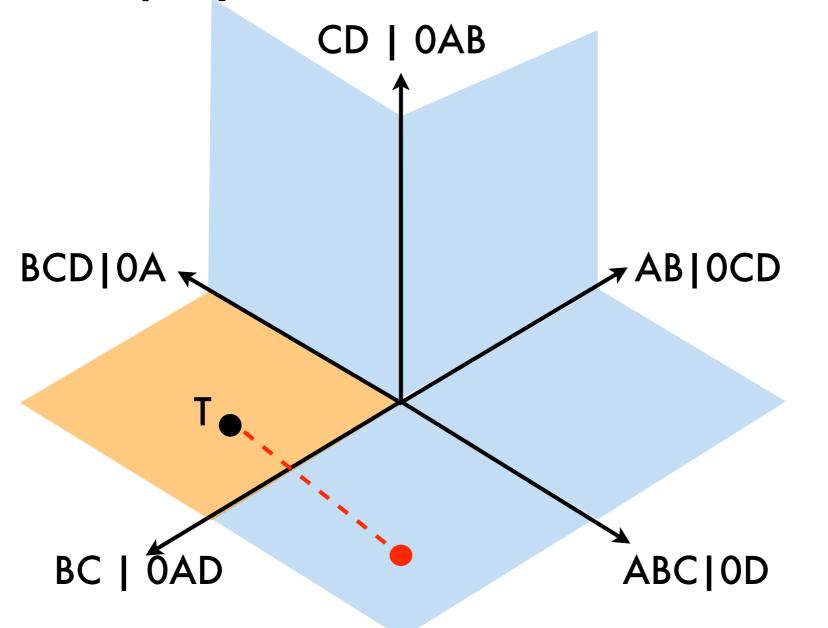


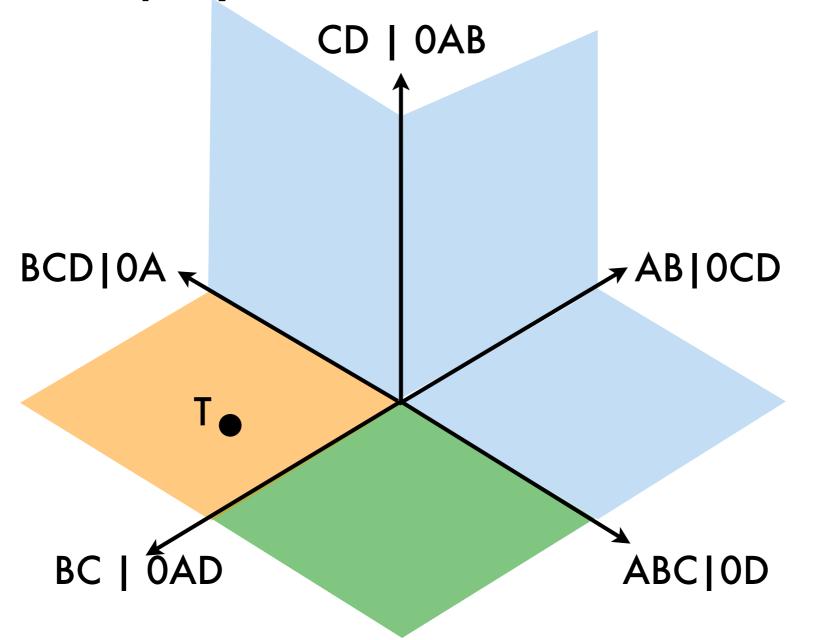


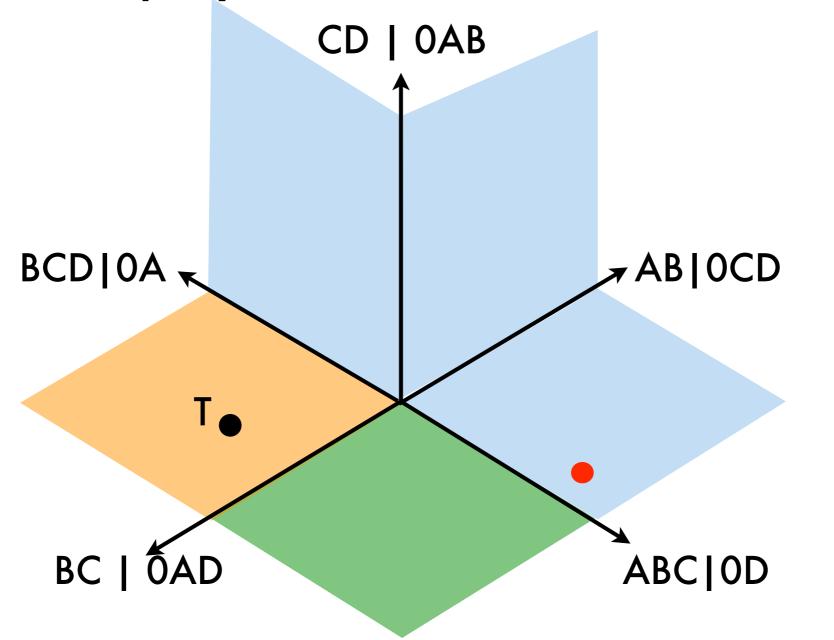


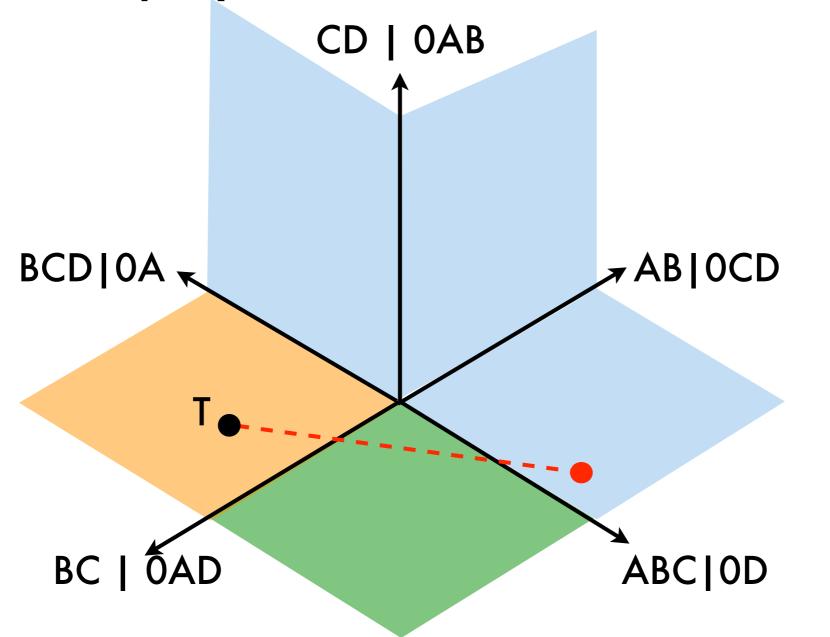


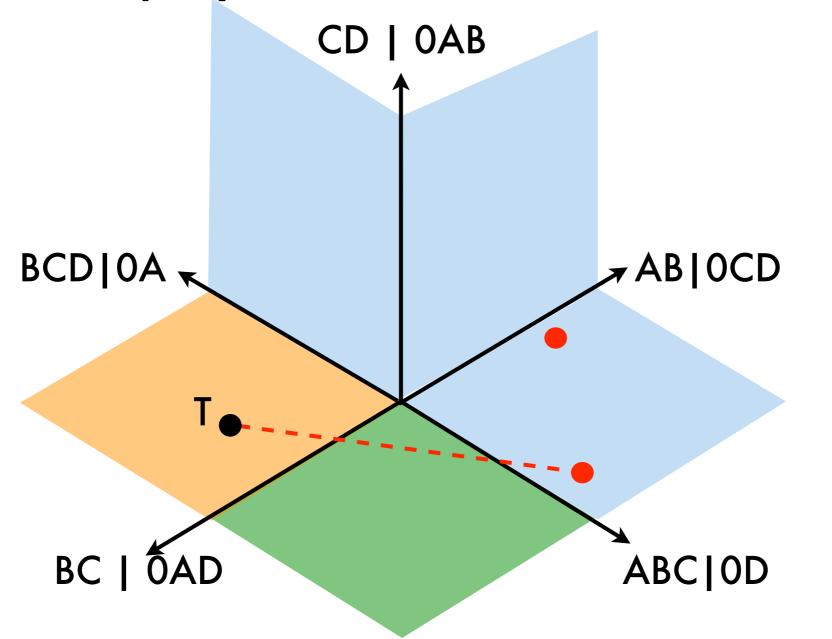


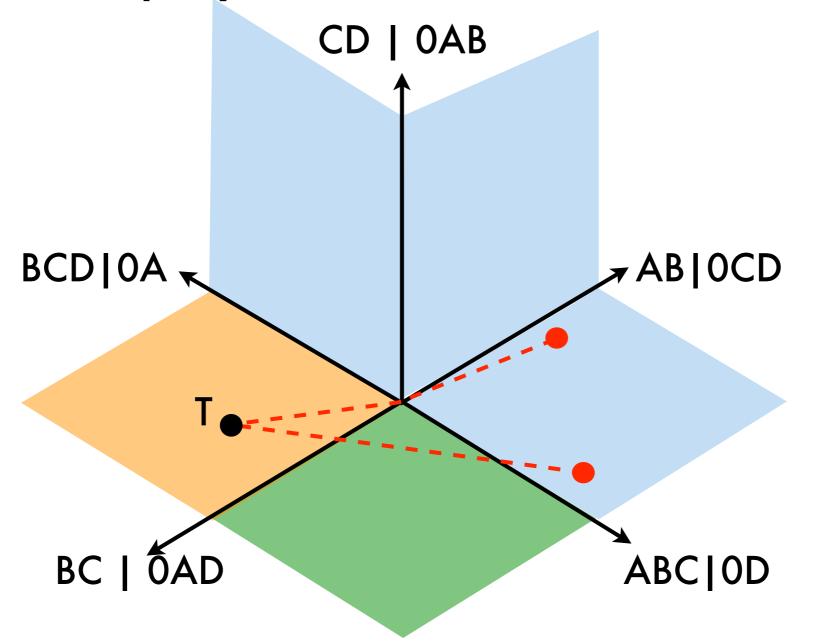


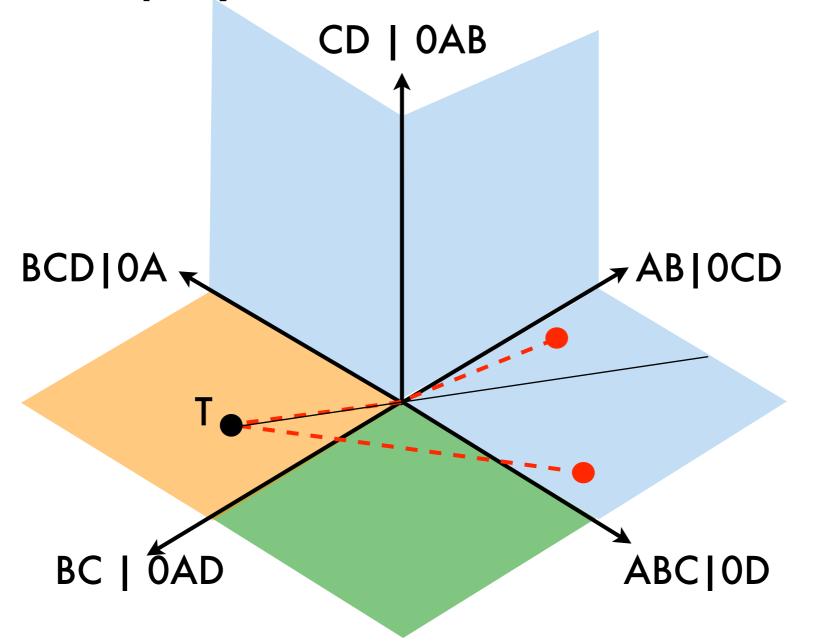


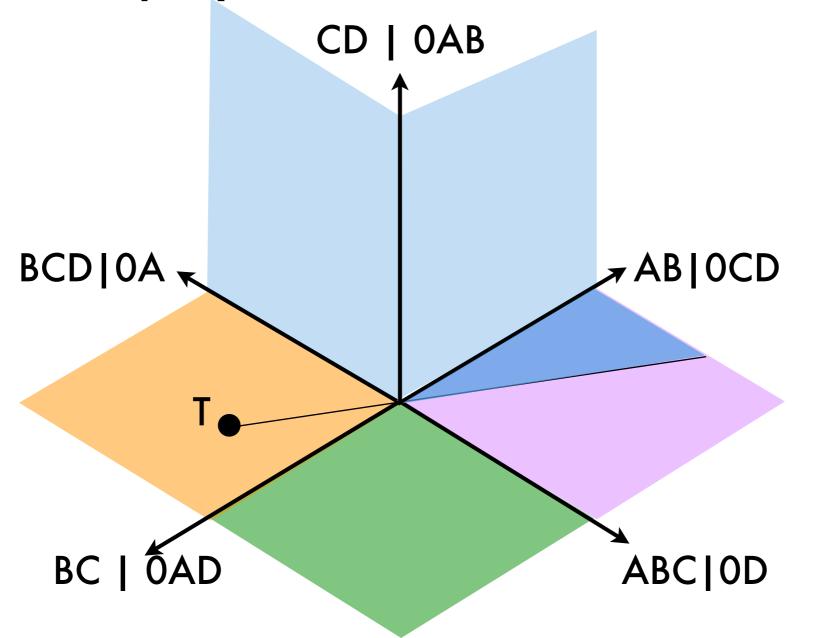












- combinatorial type of the geodesic to a fixed tree T induces a polyhedral subdivision on tree space
- use non-linear optimization to improve Sturm's algorithm:
 - once in correct polyhedral subdivision, gradient descent method will give minimum

Current and Future Work

- determine convergence of algorithm
- grouping similar trees using Principal Component Analysis
- using the geodesic distance and tree space to do statistics on trees

Thank You

• A fast algorithm for computing geodesic distances in tree space (Owen and Provan, 2010)

http://arxiv.org/abs/0907.3942

